



aerospace
climate control
electromechanical
filtration
fluid & gas handling
hydraulics
pneumatics
process control
sealing & shielding





Parker Economic Servo Package P series



北京润诚时代科技有限公司

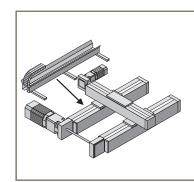
自动化事业部

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WARNING - USER RESPONSIBILITY

FAILURE OR IMPROPER SELECTION OR IMPROPER USE OF THE PRODUCTS DESCRIBED HEREIN OR RELATED ITEMS CAN CAUSE DEATH, PERSONAL INJURY AND PROPERTY DAMAGE.

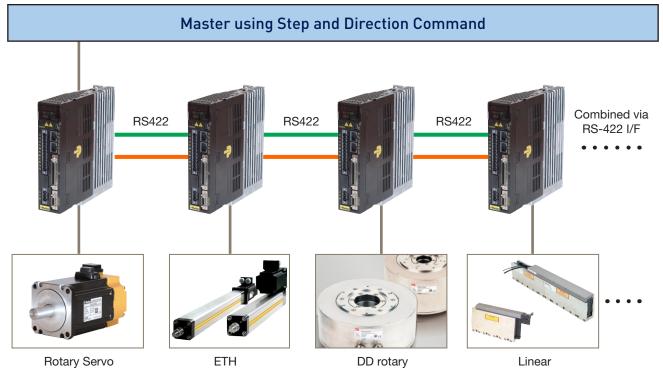
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 the application are met. The user must analyze all aspects of the application, follow applicable industry standards,
 and follow the information concerning the product in the current product catalog and in any other materials
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Powerful servo solution

Main features

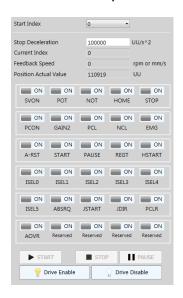
- Auto configuration (BiSS-C base)
- Multiple feedback interface
 - Serial(BiSS-C, EnDAT2.2, Tamagawa), Quadrature, SinCos
- User-friendly drive software
 - Step by step easy configuration
 - Pre-defined profile function
 - Auto tuning (real-time)
 - Various homing mode
 - Jog mode & Point to Point movement
 - 4 channel oscilloscope
 - Easy firmware update
- Programmable I/0
 - 1ms update rate
 - 16 channel digital input, 8 channel digital output
 - 2 channel analog input/output
- Various compatibility and application
 - ETH, ETT, OSPE
 - Rotary, Linear, DD servo motors and more





Pre-defined profile function

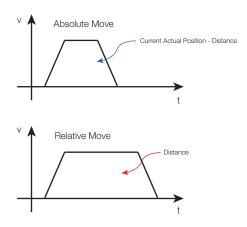
• Available 64 profiles



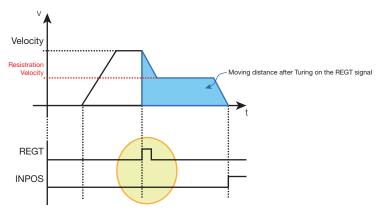


• Variable profile mode

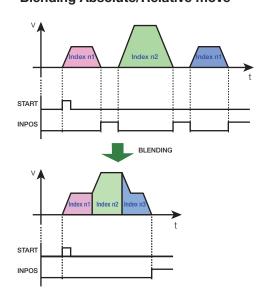
- Absolute/Relative move



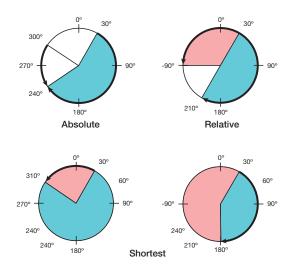
- Registration Absolute/Relative move



- Blending Absolute/Relative move

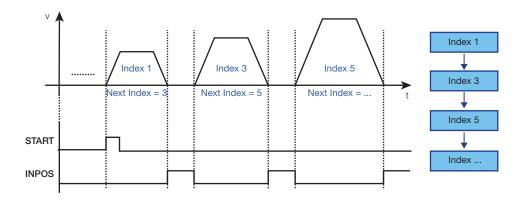


- Rotary Absolute/Relative/Shortest move



Loop method

- Go to Next Index
- Wait for Start
- Stop

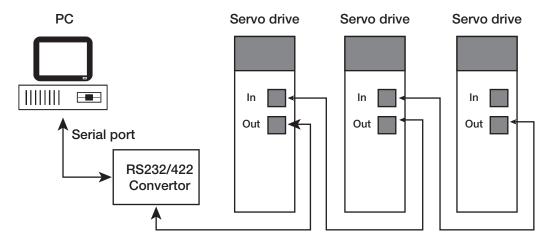


• I/O control

- Start, Stop, REG, EOS
- I/O0~5(Index number selecting & monitoring)

• Multi-drop connection

- RS422 serial communication interface for tasking ,test driving, gain turning, parameter setting and pre-defined position mode.
- This interface can be used for bus interface by using the multi-drop. (Max 32 axes)



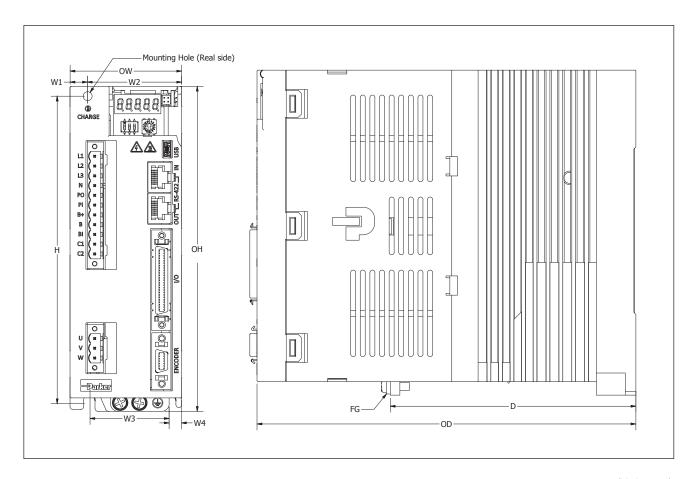
• The maximum packet size of MODBUS-RTU is 256 Byte

Ite	em	Specification
Commun	ication rule	ANSI/TIA/EIA-422 Standard
Communica	ation protocol	MODBUS-RTU
	Data bit	8 bit
Data Type	Stop bit	1 bit
	Parity	None
Syncrono	us method	Asynchronous
Bau	d rate	9600/19200/38400/57600/115200 bit for second
Available	e distance	Max. 200m
Current co	onsumption	Under 100mA

Servo Drive

Technical Data

Motor Output Power PD-01 PD-02 PD-04 PD-08	Shaft Power @ Continuous Current 300 Shaft Power @ Peak Current 300 Drive Output Power Continuous Current (RMS) 1.4 Peak Current (RMS) 4.2 Bus Voltage Drive Input Voltage Drive Control Voltage) Watts) Watts Amps	200 Watts 600 Watts 1.7 Amps 5.1 Amps	400 Watts 1,200 Watts 3.0 Amps 9.0 Amps	800 Watts 2,400 Watts 5.2 Amps					
Shaft Power @ Peak Current Drive Output Power Continuous Current (RMS) 1.4 Amps 1.7 Amps 3.0 Amps 5.2 Amps Peak Current (RMS) 1.4 Amps 1.7 Amps 3.0 Amps 5.2 Amps Peak Current (RMS) 340VDC Drive Input Voltage 230 VAC, 10, 50/60Hz Drive Control Voltage PD-10 PD-20 PD-35 Shaft Power @ Continuous Current 1,000 Watts 2,000 Watts 3,500 Watts Shaft Power @ Peak Current 3,000 Watts Continuous Current (RMS) Peak Curre	Shaft Power @ Peak Current 300 Drive Output Power Continuous Current (RMS) 1.4 Peak Current (RMS) 4.2 Bus Voltage Drive Input Voltage Drive Control Voltage) Watts Amps	1.7 Amps 5.1 Amps	1,200 Watts 3.0 Amps 9.0 Amps	2,400 Watts 5.2 Amps					
Drive Output Power Continuous Current (RMS) 1.4 Amps 1.7 Amps 3.0 Amps 5.2 Amps Peak Current (RMS) 4.2 Amps 5.1 Amps 9.0 Amps 15.6 Amps Bus Voltage 230 VAC, 30, 50/60Hz 230 VAC, 10, 50/60Hz Drive Control Voltage 230 VAC, 10, 50/60Hz Motor Output Power PD-10 PD-20 PD-35 Shaft Power @ Continuous Current 1,000 Watts 2,000 Watts 3,500 Watts Shaft Power @ Peak Current 3,000 Watts 6,000 Watts 10,500 Watts Drive Output Power 10,500 Watts 10,500 Watts 10,500 Watts Continuous Current (RMS) 6,75 Amps 13.5 Amps 16.7 Amps Peak Current (RMS) 20.25 Amps 40.5 Amps 50.1 Amps Bus Voltage 340Vdc 340Vdc 340Vdc Drive Control Voltage 230 VAC, 30, 50/60Hz 200 VAC, 30, 50/60Hz Drive Control Voltage 230 VAC, 10, 50/60Hz 230 VAC, 10, 50/60Hz Performance 62.5µ seconds ± 1 encoder count; encoder dependent Command Step and direction, CW and CCW (Positio	Drive Output Power Continuous Current (RMS) 1.4 Peak Current (RMS) 4.2 Bus Voltage Drive Input Voltage Drive Control Voltage	Amps	1.7 Amps 5.1 Amps 340	3.0 Amps 9.0 Amps	5.2 Amps					
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Peak Current (RMS)	Peak Current (RMS) 4.2 Bus Voltage Drive Input Voltage Drive Control Voltage	•	5.1 Amps 340	9.0 Amps						
Bus Voltage	Bus Voltage Drive Input Voltage Drive Control Voltage	? Amps	340		15.6 Amps					
Drive Input Voltage 230 VAC, 30, 50/60Hz	Drive Input Voltage Drive Control Voltage			/DC						
Drive Input Voltage 230 VAC, 30, 50/60Hz	Drive Input Voltage Drive Control Voltage		230 VAC 3							
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Shaft Power @ Continuous Current 1,000 Watts 2,000 Watts 3,500 Watts 3,500 Watts 3,000 Watts 3,000 Watts 10,500 Watts 10,50	Motor Output I ower	D_10	PD-20	PD-35						
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Bus Voltage Drive Input Voltage Drive Input Voltage Drive Control Voltage Deformance Def	· , , , , , , , , , , , , , , , , , , ,			•						
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Performance 62.5μ seconds Accuracy ± 1 encoder count; encoder dependent Communication Sinusoidal Input Command Enable / Reset Step and direction, CW and CCW (Position control) Enable / Reset 12-24VDC Quadrature Incremental encoder, BiSS-C (absolute) encoder, EnDAT 2.2, SinCos Output 24VDC, 120mA Brake Solid state, normally open, 1Amp @ 24VDC max Encoder Out RS-422 compatible differential driver I/O Digital input 16-channel, +24V common, selectable Digital output 8-channel, Differential (Isolated), selectable Analog input 2-channel, ±10V (max.), 12bits										
Servo update Accuracy	Drive Control Voltage		230 VAC, 1	Ø, 50/60Hz						
Servo update Accuracy										
Accuracy ± 1 encoder count; encoder dependent Communication Sinusoidal Input Command Step and direction, CW and CCW (Position control) Enable / Reset 12-24VDC Encoder Quadrature Incremental encoder, BiSS-C (absolute) encoder, EnDAT 2.2, SinCos Output Fault 24VDC, 120mA Brake Solid state, normally open, 1Amp @ 24VDC max Encoder Out RS-422 compatible differential driver I/O Digital input 16-channel, +24V common, selectable Digital output 8-channel, Differential (Isolated), selectable Analog input 2-channel, ±10V (max.), 12bits	Performance									
Accuracy ± 1 encoder count; encoder dependent Communication Sinusoidal Input Command Step and direction, CW and CCW (Position control) Enable / Reset 12-24VDC Encoder Quadrature Incremental encoder, BiSS-C (absolute) encoder, EnDAT 2.2, SinCos Output Fault 24VDC, 120mA Brake Solid state, normally open, 1Amp @ 24VDC max Encoder Out RS-422 compatible differential driver I/O Digital input 16-channel, +24V common, selectable Digital output 8-channel, Differential (Isolated), selectable Analog input 2-channel, ±10V (max.), 12bits	Servo update		62.5µ s	econds						
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Pault Fault Solid state, normally open, 1Amp @ 24VDC max Encoder Out Brake Solid state, normally open, 1Amp @ 24VDC max Encoder Out RS-422 compatible differential driver I/O Digital input 16-channel, +24V common, selectable Digital output 8-channel, Differential (Isolated), selectable Analog input 2-channel, ±10V (max.), 12bits		Step at		· ·	JOHRIOI)					
Output Fault Solid state, normally open, 1Amp @ 24VDC max Encoder Out Solid state, normally open, 1Amp @ 24VDC max Encoder Out RS-422 compatible differential driver I/O Digital input 16-channel, +24V common, selectable Digital output 8-channel, Differential (Isolated), selectable Analog input 2-channel, ±10V (max.), 12bits		O			t-\					
Output Fault Solid state, normally open, 1Amp @ 24VDC max Encoder Out Solid state, normally open, 1Amp @ 24VDC max RS-422 compatible differential driver I/O Digital input 16-channel, +24V common, selectable Digital output 8-channel, Differential (Isolated), selectable Analog input 2-channel, ±10V (max.), 12bits	Encoder	Quadrature			te) encoder,					
Fault 24VDC, 120mA Brake Solid state, normally open, 1Amp @ 24VDC max RS-422 compatible differential driver I/O Digital input 16-channel, +24V common, selectable Digital output 8-channel, Differential (Isolated), selectable Analog input 2-channel, ±10V (max.), 12bits			ENDAI 2	z, Sincos						
Fault 24VDC, 120mA Brake Solid state, normally open, 1Amp @ 24VDC max RS-422 compatible differential driver I/O Digital input 16-channel, +24V common, selectable Digital output 8-channel, Differential (Isolated), selectable Analog input 2-channel, ±10V (max.), 12bits										
Brake Solid state, normally open, 1Amp @ 24VDC max RS-422 compatible differential driver I/O Digital input 16-channel, +24V common, selectable Digital output 8-channel, Differential (Isolated), selectable Analog input 2-channel, ±10V (max.), 12bits			20/20	100 1						
I/O Digital input Digital output Analog input RS-422 compatible differential driver RS-422 compatible differential driver RS-422 compatible differential driver 16-channel, +24V common, selectable 8-channel, Differential (Isolated), selectable 2-channel, ±10V (max.), 12bits										
I/O Digital input 16-channel, +24V common, selectable Digital output 8-channel, Differential (Isolated), selectable Analog input 2-channel, ±10V (max.), 12bits										
Digital input16-channel, +24V common, selectableDigital output8-channel, Differential (Isolated), selectableAnalog input2-channel, ±10V (max.), 12bits	Encoder Out		RS-422 compatible	e differential driver						
Digital input16-channel, +24V common, selectableDigital output8-channel, Differential (Isolated), selectableAnalog input2-channel, ±10V (max.), 12bits										
Digital output 8-channel, Differential (Isolated), selectable 2-channel, ±10V (max.), 12bits	· · · · · · · · · · · · · · · · · · ·									
Analog input 2-channel, ±10V (max.), 12bits										
	Digital output	8-c	channel, Differentia	l (Isolated), selecta	ble					
Analog output 2-channel +10V (max.) selectable 12bits	Analog input									
Z Orialitol, 2107 (maxi), coloctable, 12bite	Analog output	2-channel, ±10V (max.), selectable, 12bits								
			•							
Communications	Communications									
LISB 2.0 for firmware upload and drive configuration		USB 2.0	0 for firmware uplo	ad and drive confid	uration					
Type RS422 for operation interface	Type									
Standard ANSI/ TIA/ EIA-422 standard	Standard	<u> </u>								
Baud Rate 9,600/ 19,200/ 38,400/ 57,600/ 115,200 bps										
2,000, 10,200, 01,000, 110,200,000	2000 1000	0,00		,	-					
Standards CE, RoHS	Standards	CE, RoHS								
Otanuarus OE, NONS	Giaridalus		U⊑, F	10110						
	Environmental									
			0 5000 //	20 400.05\						
Environmental			,	,						
Environmental Temperature 0 - 50 °C (32 - 122 °F)										
Environmental Temperature 0 - 50 °C (32 - 122 °F) Humidity 0 - 90% non-condensing	Shock / Vibration	15	g, 11msec half sig	n / 10-2,000Hz @ 2	<u>2g</u>					



(Unit: mm)

		PD-01 ~ 04	PD-08 / 10	PD-20 / 35
Н	Height	158	158	158
ОН	Overall Height	169	169	169
OW	Overall Width	38	58	88
W1	Width 1	6	10	44
W2	Width 2	26	48	44
W3	Width 3	32	42	78
W4	Width 4	6	6	5
D	Depth	107.7	127.7	112.5
OD	Overall Depth	173	197	198

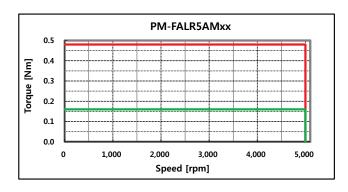
Note)

- This is for your reference only. For exact dimension, please refer to the drawing file available from http://solutions.parker.com/AUG_EM.
- Specification subject to change without notice.

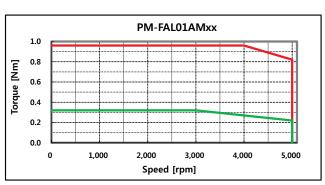
Servo Motor (FAL Series Motor)

Technical Data

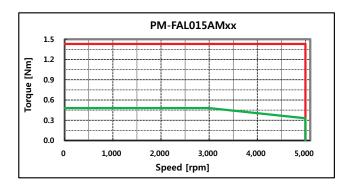
Motor	Output Power		PM-FALR5AMxx	PM-FAL01AMxx	PM-FAL015AMxx				
	Rated Output Power		50 Watts	100 Watts	150 Watts				
Motor	Output Torque								
	Dated Targue	N-m	0.16	0.32	0.48				
	Rated Torque	kgf-cm	1.62	3.25	4.87				
	Instantaneous Peak	N-m	0.48	0.96	1.43				
	Torque	kgf-cm	4.87	9.74	14.62				
Motor	Speed								
	Rated Speed			3000 rpm					
	Peak Speed			5000 rpm					
Momo	ent of Inertia	kg-m² x 10-4	0.02	0.05	0.06				
WOTTE	ent of mertia	gf-cm-s ²	0.02	0.05	0.07				
Availa	ble Moment of Load Inertia		Motor Inc	ertia x 30	x 20				
Position	on Feedback		E	BiSS-C Interface - 18bi	it				
Weigh	nt		0.4kg 0.5kg 0.7kg						
Stand	ards			CE					
Enviro	onmental								
	Temperature		0 - 40 °C						
	Humidity		2	0-80% non-condensin	g				

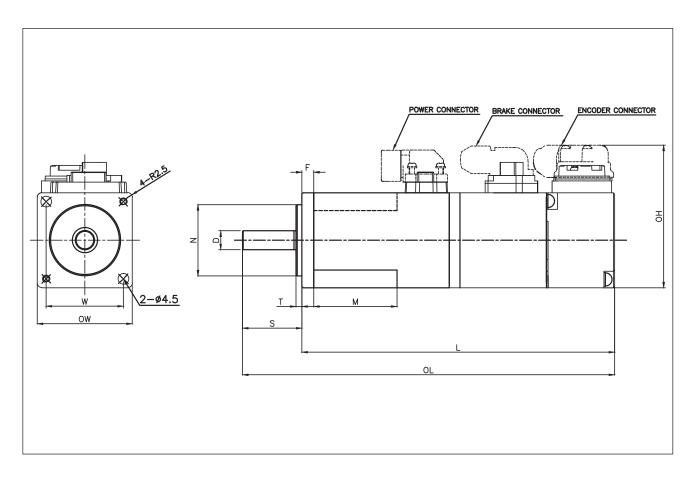


Shock / Vibration



5G (49m/s²)





(Unit: mm)

	OW	ОН	OL	L	N	W	D	F	М	S	Т
PM-FALR5AMN			103.2	78.2					23		
PM-FAL01AMN			120.2	95.2					35		
PM-FAL015AMN	40	60	140.2	115.2	20	20.5	8	5	35	05	2.5
PM-FALR5AM2	40	60	139.6	114.6	30	32.5	0	5	23	25	2.5
PM-FAL01AM2			156.6	131.6					35		
PM-FAL015AM2			176.6	151.6					35		

- FAL series are no-key type, Detail drawings and N-T curves are available at http://solutions.parker.com/AUG_EM
 Specification subject to change without notice.

Servo Motor (FBL Series Motor)

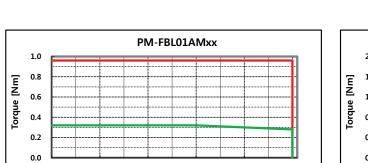
Technical Data

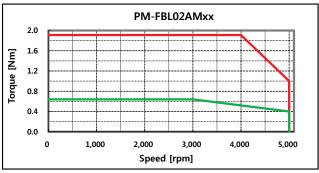
Humidity

Shock / Vibration

1,000

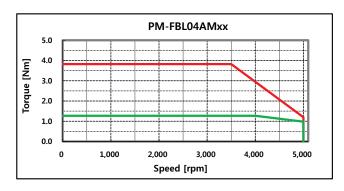
Motor	Output Power		PM-FBL01AMxx	PM-FBL02AMxx	PM-FBL04AMxx				
	Rated Output Power		100 Watts	200 Watts	400 Watts				
Motor	Output Torque								
	Rated Torque	N-m	0.32	0.64	1.27				
	nateu Torque	kgf-cm	3.25	6.50	12.99				
	Instantaneous Peak	N-m	0.96	1.91	3.82				
	Torque	kgf-cm	9.74	38.98					
Motor	Speed								
	Rated Speed			3000 rpm					
	Peak Speed			5000 rpm					
Momo	ent of Inertia	kg-m ² x 10-4	0.09	0.15	0.25				
WOTTE	ent of intertia	gf-cm-s ²	0.09	0.15	0.25				
Availa	ble Moment of Load Inertia			Motor Inertia x 20					
Position	on Feedback		BiSS-C Interface – 19bit						
Weigh	t		0.7kg	0.9kg	1.3kg				
Stand	ards		CE						
Enviro	nmental								
	Temperature			0 - 40 °C					



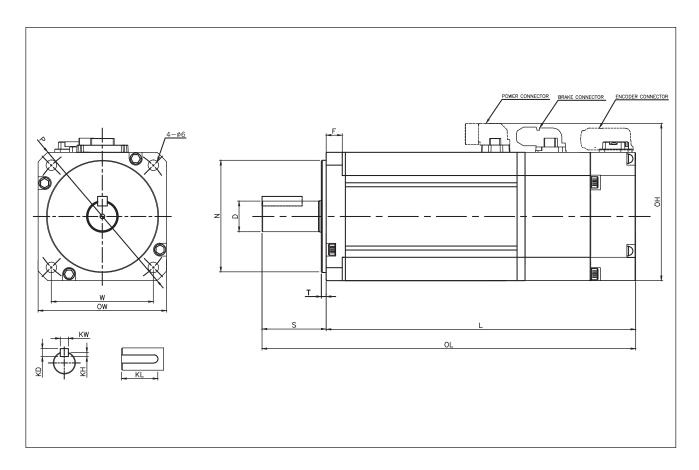


20-80% non-condensing

5G (49m/s²)



Speed [rpm]



(Unit: mm)

	OW	ОН	OL	L	N	W	D	F	S	Т	KW	KH	KD	KL	Р
PM-FBL01AMN			107.2	77.2											
PM-FBL02AMN			118.2	88.2											
PM-FBL04AMN	62	80	138.2	108.2	50	49.5	14	6	30	3	5	3	5	22.5	80
PM-FBL01AMK2	02	80	147.2	117.2	50	10.0	14	0	30	3	5	3	5	22.0	
PM-FBL02AMK2			158.2	128.2											
PM-FBL04AMK			178.2	148.2											

- Detail drawings and N-T curves are available at http://solutions.parker.com/AUG_EM
 Specification subject to change without notice.

Servo Motor (FCL Series Motor)

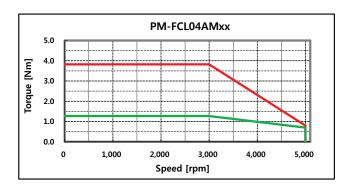
Technical Data

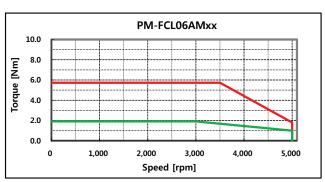
Temperature

Shock / Vibration

Humidity

Motor	Output Power		PM-FCL04AMxx	PM-FCL06AMxx	PM-FCL08AMxx	PM-FCL10AMxx				
	Rated Output Power		400 Watts	600 Watts	750 Watts	1000 Watts				
Motor	Output Torque									
	Poted Torque	N-m	1.27	1.91	2.39	3.18				
	Rated Torque	kgf-cm	13	19.5	24.36	32.5				
	Instantaneous Peak	N-m	3.82	5.73	7.16	9.55				
	Torque	kgf-cm	38.98	38.98 58.47 73.08						
Motor	Speed									
	Rated Speed			3000	rpm					
	Peak Speed			5000	rpm					
Mana	ent of Inertia	kg-m ² x 10-4	0.5	0.88	1.25	1.62				
Mome	ent of mertia	gf-cm-s ²	0.51	0.89	1.27	1.65				
Availal	ble Moment of Load Ine	rtia	Motor Inertia x 15							
Positio	on Feedback		BiSS-C Interface – 19bit							
Weigh	t		1.6kg	2.2kg	2.7kg	3.8kg				
Standa	ards			C	E					
Enviro	nmental									

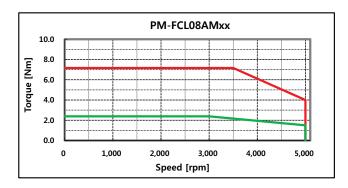


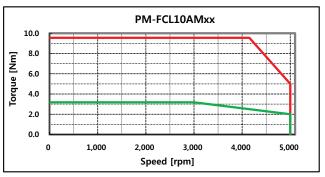


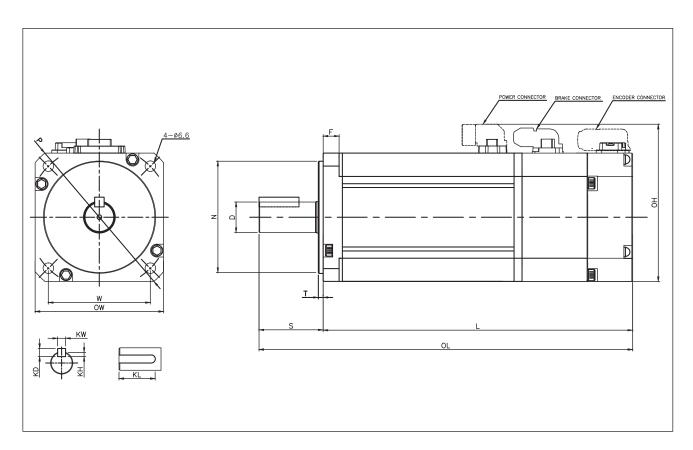
0 - 40 °C

20-80% non-condensing

5G (49m/s²)







(Unit: mm)

	OW	ОН	OL	L	N	W	D	F	S	Т	KW	KH	KD	KL	Р
PM-FCL03DMK PM-FCL04AMK			138.7	98.7			14				5	3	5		
PM-FCL05DMK PM-FCL06AMK			156.7	116.7											
PM-FCL06DMK PM-FCL08AMK			174.7	134.7			19				6	3.5	6		
PM-FCL07DMK PM-FCL10AMK	80	98	192.7	152.7	70	63.6		10	40	3				25	105
PM-FCL03AMK2 PM-FCL04AMK2	00	90	179	139	70	03.0	14	10	40	3	5	3	5	23	103
PM-FCL05DMK2 PM-FCL06AMK2			197	157											
PM-FCL06DMK2 PM-FCL08AMK2			215	175			19				6	3.5	6		
PM-FCL07DMK2 PM-FCL10AMK2			233	193											

Note)

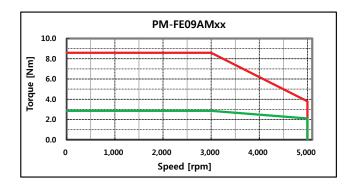
- Detail drawings and N-T curves are available at http://solutions.parker.com/AUG_EM
 Specification subject to change without notice.

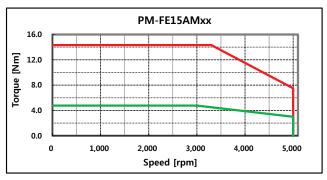
Servo Motor (FE Series Motor)

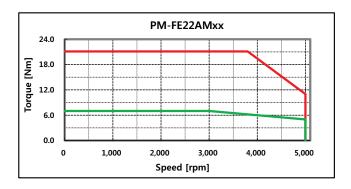
Technical Data

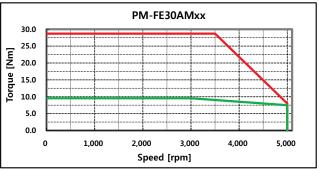
Motor	Output Power		PM-FE09AMxx	PM-FE15AMxx	PM-FE22AMxx	PM-FE30AMxx				
	Rated Output Power		900 Watts	1500 Watts	2200 Watts	3000 Watts				
Motor	Output Torque									
	Poted Torque	N-m	2.86	4.77	7	9.55				
	Rated Torque	kgf-cm	29.2	48.7	71.4	97.4				
	Instantaneous Peak	N-m	8.59	14.32	21.01	28.65				
	Torque	kgf-cm	87.7	87.7 146.1 214.3 2						
Motor	Speed									
	Rated Speed			3000	rpm					
	Peak Speed		5000 rpm							
Mana	ent of Inertia	kg-m ² x 10-4	5.66	10.18	14.62	19.04				
IVIOITIE	ent of mertia	gf-cm-s ²	5.77 10.39 14.92 19.4							
Availa	ble Moment of Load Ine	rtia		Motor Inc	ertia x 10					
Positi	on Feedback			BiSS-C Inte	rface – 19bit					
Weigh	it		5.0kg	6.7kg	8.5kg	10.1kg				

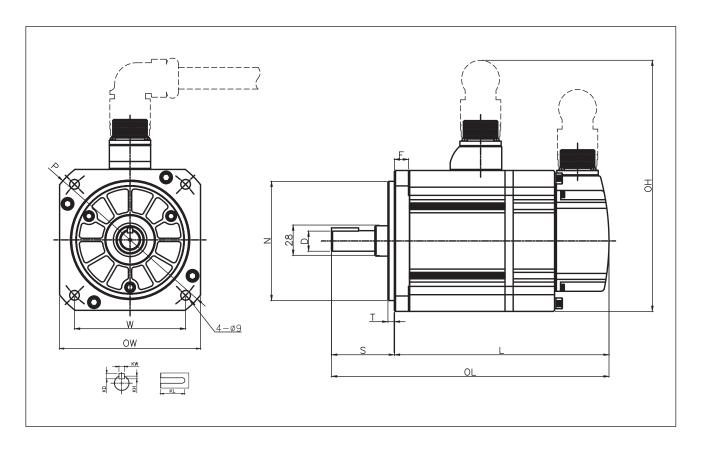
Standards	CE
Environmental	
Temperature	0 - 40 °C
Humidity	20-80% non-condensing
Shock / Vibration	5G (49m/s²)











(Unit: mm)

	OW	ОН	OL	L	N	W	D	F	S	Т	KW	KH	KD	KL	Р
PM-FE03MMK PM-FE05GMK PM-FE06DMK PM-FE09AMK			197.3	139.3			19				5	3	5		
PM-FE06MMK PM-FE09GMK PM-FE11DMK PM-FE15AMK			217.3	159.3			19				3	3	J		
PM-FE09MMK PM-FE13GMK PM-FE16DMK PM-FE22AMK			237.3	179.3			22				6	3.5	6		
PM-FE12MMK PM-FE17GMK PM-FE22DMK PM-FE30AMK	120	001.7	255.3	197.3	110	100 5	24	13	58	6	8	4	7	25	165
PM-FE03MMK2 PM-FE05GMK2 PM-FE06DMK2 PM-FE09AMK2	130	130 231.7	235.3	177.3		102.5	19	13	56	0	5	3	5	25	165
PM-FE06MMK2 PM-FE09GMK2 PM-FE11DMK2 PM-FE15AMK2			255.3	197.3		19				5	3	5			
PM-FE09MMK2 PM-FE13GMK2 PM-FE16DMK2 PM-FE22AMK2			275.3	217.3			22				6	3.5	6		
PM-FE12MMK2 PM-FE17GMK2 PM-FE22DMK2 PM-FE30AMK2			293.3	235.3			24				8	4	7		

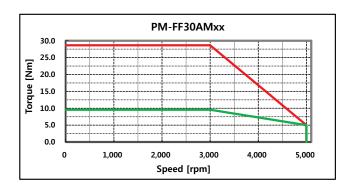
Note)

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 Specification subject to change without notice.

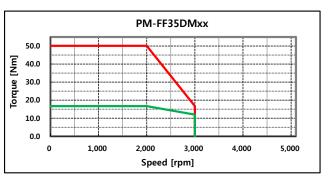
Servo Motor (FF Series Motor)

Technical Data

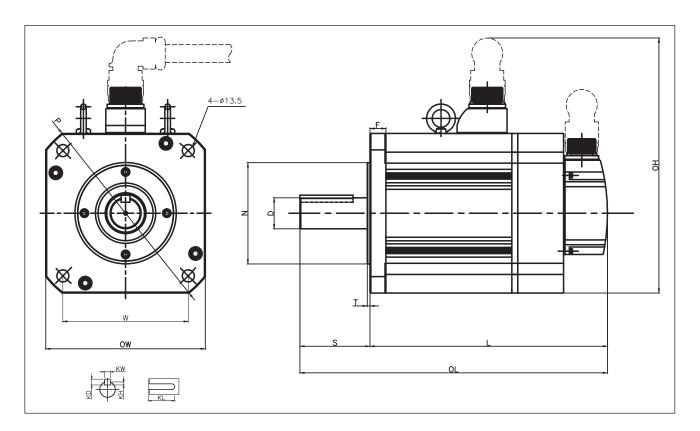
Motor Output Power			PM-FF30AMxx	PM-FF35DMxx				
	Rated Output Power		3000 Watts	3500 Watts				
Motor Output Torque								
	Poted Torque	N-m	9.55	16.70				
	Rated Torque	kgf-cm	97.4	170.4				
	Instantaneous Peak	N-m	28.65	50.10				
	Torque	kgf-cm	292.3	511.40				
Motor Speed								
	Rated Speed		3000 rpm	2000 rpm				
	Peak Speed		5000 rpm	3000 rpm				
Mama	Moment of Inertia $\frac{\text{kg-m}^2 \times 10\text{-4}}{\text{gf-cm-s}^2}$		27.96	46.56				
MOTTE			28.53	47.51				
Available Moment of Load Inertia			Motor Inertia x 5					
Position Feedback			BiSS-C Interface - 19bit					
Weigh	it		12.5kg	17.4kg				
Standards			CE					
Environmental								
	Temperature		0 - 40 °C					
	Humidity		20-80% non-condensing					



Shock / Vibration



5G (49m/s²)



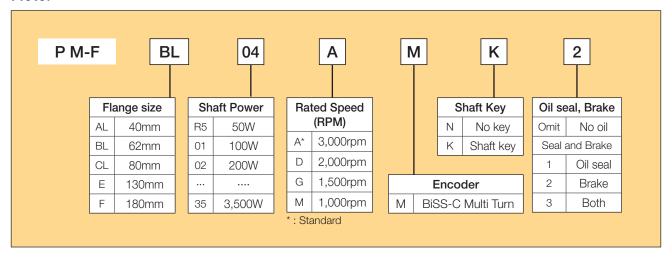
(Unit: mm)

	OW	ОН	OL	L	N	W	D	F	S	Т	KW	KH	KD	KL	Р
PM-FF12MMK PM-FF20GMK PM-FF22DMK PM-FF30AMK		0 287.7	257.5	178.5	114.3	141.4	35	17	79	3	10	5	8	60	230
PM-FF20MMK PM-FF30GMK PM-FF35DMK			287.5	208.5											
PM-FF30MMK	100		331.5	252.5											
PM-FF12MMK2 PM-FF20GMK2 PM-FF22DMK2 PM-FF30AMK2	180		308.9	229.9											
PM-FF20MMK2 PM-FF30GMK2 PM-FF35DMK2			338.9	259.9											
PM-FF30MMK2			382.9	303.9											

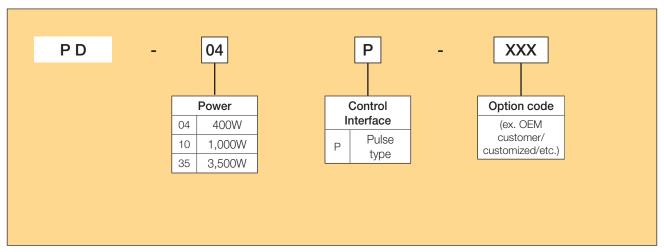
- Note)
 Detail drawings and N-T curves are available at http://solutions.parker.com/AUG_EM
 Specification subject to change without notice.

Ordering Code

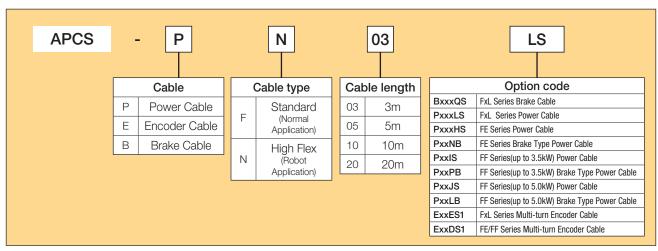
Motor



Drive



Cable



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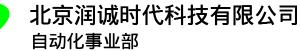
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- 12. <u>Cancellations and Changes.</u> Orders shall not be subject to cancellation or change by Buyer for any reason, except with Seller's written consent and upon terms that will indemnify, defend and hold Seller harmless against all direct, incidental and consequential loss or damage. Seller may change product features, specifications, designs and availability with notice to Buyer.
- Limitation on Assignment. Buyer may not assign its rights or obligations under this agreement without the prior written consent of Seller.
- 14. Force Majeure. Seller does not assume the risk and shall not be liable for delay or failure to perform any of Seller's obligations by reason of circumstances beyond the reasonable control of Seller (hereinafter "Events of Force Majeure"). Events of Force Majeure shall include without limitation: accidents, strikes or labor disputes, acts of any government or government agency, acts of nature, delays or failures in delivery from carriers or suppliers, shortages of materials, or any other cause beyond Seller's reasonable control.
- 15. Waiver and Severability. Failure to enforce any provision of this agreement will not waive that provision nor will any such failure prejudice Seller's right to enforce that provision in the future. Invalidation of any provision of this agreement by legislation or other rule of law shall not invalidate any other provision herein. The remaining provisions of this agreement will remain in full force and effect.
- 16. Termination. Seller may terminate this agreement for any reason and at any time by giving Buyer thirty (30) days written notice of termination. Seller may immediately terminate this agreement, in writing, if Buyer: (a) commits a breach of any provision of this agreement (b) appointments a trustee, receiver or custodian for all or any part of Buyer's property (c) files a petition for relief in bankruptcy on its own behalf, or by a third party (d) makes an assignment for the benefit of creditors, or (e) dissolves or liquidates all or a majority of its assets.
- 17. Governing Law. This agreement and the sale and delivery of all Products hereunder shall be deemed to have taken place in and shall be governed and construed in accordance with the laws of the State of Ohio, as applicable to contracts executed and wholly performed therein and without regard to conflicts of laws principles. Buyer irrevocably agrees and consents to the exclusive jurisdiction and venue of the courts of Cuyahoga County, Ohio with respect to any dispute, controversy or claim arising out of or relating to this agreement.
- 18. Indemnity for Infringement of Intellectual Property Rights. Seller shall have no liability for infringement of any patents, trademarks, copyrights, trade dress, trade secrets or similar rights except as provided in this Section. Seller will defend and indemnify Buyer against allegations of infringement of U.S. patents, U.S. trademarks, copyrights, trade dress and trade secrets ("Intellectual Property Rights"). Seller will defend at its expense and will pay the cost of any settlement or damages awarded in an action brought against Buyer based on an allegation that a Product sold pursuant to this Agreement infringes the Intellectual Property Rights of a third party. Seller's obligation to defend and indemnify Buyer is contingent on Buyer notifying Seller within ten (10) days after Buyer becomes aware of such allegations of infringement, and Seller having sole control over the defense of any allegations or actions including all negotiations for settlement or compromise. If a Product is subject to a claim that it infringes the Intellectual Property Rights of a third party, Seller may, at its sole expense and option, procure for Buyer the right to continue using the Product, replace or modify the Product so as to make it noninfringing, or offer to accept return of the Product and return the purchase price less a reasonable allowance for depreciation. Notwithstanding the foregoing, Seller shall have no liability for claims of infringement based on information provided by Buyer, or directed to Products delivered hereunder for which the designs are specified in whole or part by Buyer, or infringements resulting from the modification, combination or use in a system of any Product sold hereunder. The foregoing provisions of this Section shall constitute Seller's sole and exclusive liability and Buyer's sole and exclusive remedy for infringement of Intellectual Property Rights.
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- 20. Compliance with Law, U. K. Bribery Act and U.S. Foreign Corrupt Practices Act. Buyer agrees to comply with all applicable laws and regulations, including both those of the United Kingdom and the United States of America, and of the country or countries of the Territory in which Buyer may operate, including without limitation the U. K. Bribery Act, the U.S. Foreign Corrupt Practices Act ("FCPA") and the U.S. Anti-Kickback Act (the "Anti-Kickback Act"), and agrees to indemnify and hold harmless Seller from the consequences of any violation of such provisions by Buyer, its employees or agents. Buyer acknowledges that they are familiar with the provisions of the U. K. Bribery Act, the FCPA and the Anti-Kickback Act, and certifies that Buyer will adhere to the requirements thereof. In particular, Buyer represents and agrees that Buyer shall not make any payment or give anything of value, directly or indirectly to any governmental official, any foreign political party or official thereof, any candidate for foreign political office, or any commercial entity or person, for the purpose of influencing such person to purchase products or otherwise benefit the business of Seller.

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August 2014



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